

User Manual



Radiolink Electronic Limited

www.radiolink.com



Introduction

Thank you for purchasing Radiolink little racing drone -- F110.

F110 is R&D by RadioLink, it can throw and start to fly in any angle, fly in cycle mode just controlled by rudder stick, also can keep head front forward point without compass.

F110, controlled by Radiolink brand new mini racing drone flight controller CS360, different from other flight controllers that need to set PID tuning before use, gets the perfect parameters and flight angle automatically, is the best choice for the RC beginners.

Suggestion: In order to fully enjoy the benefits of this racing drone and ensure flight safety, please read the instructions carefully and set up the device as described below, when we write this instruction, we try our best to use the familiar and simple words to make it easy for beginners to understand the name and formulation.

Please refer to the manual or call our after-sales (+86-0755-88361717) or log in BBS (such as <u>www.rcgroups.com</u>,

<u>https://www.facebook.com/Radiolink-1455452961436694/</u>) to check the issues related answer to questions if you have any questions.

Due to unforeseen changes in production procedures, the information contained in this manual is subject to change without notice.

More information please check our website as below:

http://www.radiolink.com

After-Sales Information

Any technical updates and manual corrections will be available on our website. If you do not find the answers to your questions there, please via email for the most rapid and convenient response.

FOR AFTER-SALES SERVICE:

Please start here for getting more service.

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Note: About flying

While you are getting ready to fly, if you place your transmitter on the ground, be sure that the wind won't tip it over. If it is knocked over, the throttle stick may be accidentally moved, causing the engine to speed up. Also, damage to your transmitter may occur.

Warning!!!

This product is not a toy and is not suitable for children under the age of 18. Adults should keep the product out of the reach of children and exercise caution when operating this product in the presence of children.

Please don't fly in the rain!

Rain or moisture may enter the transmitter internal through gaps in the antenna or joystick flight and cause your flight to instability even out of control. If inevitable will fly in the wet weather (such as game), please be sure to use plastic bags or waterproof cloth to cover your transmitter, please don't flight if there is lightning.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and

(2) This device must accept any interference received, including interference that may cause undesired operation.

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.



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1. Features Highlights

- (1) Can Throw and Start to Fly in Any Angle
- (2) Cycle Mode Just Controlled by Rudder Stick

(3) Head Front Forward Point Without Compass: Drone head always towards the same direction if not move rudder stick, otherwise the head direction will change according to rudder stick move.

(4) PID Parameter Tune Automatically: F110, controlled by Radiolink brand new mini racing drone flight controller CS360, different from other flight controllers that need to set PID tuning before use, gets the perfect parameters and flight angle automatically.

Specification

- (1) Weight (include packing box): 170g
- (2) F110 Size (without propeller): 110mm*44mm
- (3) Packing Box Size: 225*125*55mm
- (4) Flight Controller CS360 size: 32.5*21.5mm
- (5) R6DSM Size: 15*13mm
- (6) Propeller diameter: 55mm
- (7) Flight Time : 6 to 8 min(1S 600mA, 25C Li-Po battery)
- (8) Operating Temperature : depends on your battery
- (9) Control distance: 600 meters air(with R6DSM)
- (10) Support Transmitters: all transmitters that support S-BUS receiver
- (11) Coreless Motor: 8520
- (12) O-ring for Motor Size: 8*15*6mm, rubber

2. Compatible with Remote Controllers

F110 compatible with RadioLink remote controllers AT10, AT10II, AT9, AT9S and T8FB.

F110 will sell with receiver R6DSM or R8FM (you can buy F110 with R6DSM or F110 with R8FM from our dealer).

R6DSM compatible with RadioLink remote controllers AT10, AT10II, AT9, AT9S.

R8FM compatible with RadioLink remote controller T8FB.

3. Preparing Before Flight

3.1 Charge

First, please keep your battery is 4.2V to ensure your F110 with enough power to fly, you can charge your battery by CM120 if not fully charged.

Professional Designed LiPo Battery Charger CM120

Energy Supply Station

Brand new designed LiPo battery charger CM120, designed for 1S LiPo battery. Inherit the high precision of CB86PLUS, make the charging more safe, battery which



charged by CM120 is more powerful can flight about five to eight minutes. Charging current can setup 1A or 2A by toggle the switch as you need.



Red LED indicate charging mode and green LED indicate the battery is fully charged. CM120 use universal USB connector, so you can use computer or power bank for mobile phone as the power supply for CM120.

Pay attention: ensure the voltage output of power supply is not higher than 5V.

3.2 Remote Controller Setup Setup If Controlled by AT9S/AT9/AT10/AT10II

(1) Please turn on AT9S/AT9(DC 7.4~18V) or AT10/AT10II(DC 7.4~15V) first.

(2) Make sure the model type of AT9S/AT9/AT10/AT10II is multirotor model, and the CH3(throttle) is reverse.



Setup in BASIC MENU--MODEL TYPE--MULTIROTOR

Back to BASIC MENU---REVERSE--setup 3: THRO REV

RadioLink					Radiolink Electronic Limit <u>www.radiolink.co</u>		
BASTC NENT	1			[REVERSE]			
< MULTIROTO		de1-011 >			1:AILE	NOR	
		MOT OIL >			2:ELEV	NOR	
PARAMETER	D/R, EXP	TIMER		CH3:THKU	3:THRØ	REV	
NODEL SEL.	MOTOR CUT	TRAINER		INFW MOD	4:RUDD	NOR	
NODEL TYPE		LOGIC SW		KEW NOK	5:ATTI	NOR	
END POINT	TRIM	SERVO			6:AUX1	NOR	
SUB-TRIM	F/S	RECEIVE		CH9 : NOR	7:AUX2	NOR	
REVERSE	AUX-CH	SYSTEM		CH10: NOR	8:AUX3	NOR	

Setup in ADVANCE MENU--ATTITUDE--CH:CH5, SW3:SwC

Setup both up and center position of SwC STABL. Model and down position AUTO model or other mode.

[advance menu]		[ATTITUDE]		
< MULTIROTOR	Model-011 >	CH:CH5 S	H3:SHC	SW2:NUL
ATTITUDE		STABL. : 0%	-posi- (UP-UP)	-swt- (OFF)
THR-CURVE		- STABL. : 50%	(CT-UP)	(OFF)
PROG. MIX		AUTO :100%	(DN-UP)	(ON)
SERVO DLY		HOVER : 25%	(UP-DN)	(OFF)
		F/S: 75%	(CT-DN)	(OFF)
		AUX : 50%	(DN-DN)	(OFF)
			4	
	•			
. 1				
AT95	Stablilize Mode			Stablilize Mode
RadioLink	Stablilize Mode	RedioLink	100	Stablilize Mode
	Low Speed Mode			Low Speed Mode

AT9S/AT9/AT10/AT10II: SwC at the up or center position shows that F110 will flight in Stabilize Mode while SwC at the bottom position shows that F110 flight in Low Speed Mode.

Setup If Controlled by T8FB

(1) Please turn on T8FB(DC 4.8~18V) first.

(2) Make sure the model type of T8FB is multirotor model, and the CH3(throttle) is reverse.



If you need change parameters, please connect T8FB and computer via a universal android USB cable, setup details please read the T8FB user manual(you can download from our website <u>www.radiolink.com</u>).

T8FB: SwB at the up or center position shows that F110 will flight in Stabilize Mode while SwB at the bottom position shows that F110 flight in Low Speed Mode.



3.3 Power On and Bind

3.3.1 Power On

(1) Orange propellers default indicate the head direction, if you change the propellers, you can make sure the head direction by check the flight controller CS360(like the picture), make sure before power F110 on.





(2) Please put the F110 on a level surface, the green LED will blinking after power on about 2 seconds, do not move F110 when green LED blinking.

(3) F110 finished the calibration after green LED off.

Attention: Head direction have been determinate, if you put not same as the direction that when you calibrate, it will back to the same direction automatically when F110 start to fly, that we called Head Front Forward Point Without Compass.

3.3.2 Bind

F110 sells with receiver R6DSM or R8FM .

- (1) Place the transmitter and the receiver close to each other within 1 meters.
- (2) Turn on the transmitter, then power on the R6DSM or R8FM.
- (3) Connect R6DSM or R8FM to flight controller CS360(it default connect).

(4) There is a black button on the R6DSM and R8FM, press the binding button twice in two seconds and release, receiver light start blinking, after about 8 times blinking, match code success when receiver signal LED always on!

Attention: If your transmitter is AT10II, it will default that the channel is setup 12CH, you have to setup channel from 12CH to 10CH in SYSTEM menu because R6DSM is a 10 channels receiver.(AT9, AT9S and AT10 are the same)

F110 now just support S-BUS signal, both R6DSM and R8FM support S-BUS and PPM signal, please make sure that the LED of R6DSM/R8FM is blue which shows R6DSM/R8FM output S-BUS signals.



Both R6DSM and R8FM can recognize signal by check the bind LED. Blue/purple LED indicates S-BUS signal and red LED indicates PPM signal.

If you need change signal from PPM to S-BUS, please short press the ID SET switch two times within 1 second, the signal is changed from SBUS to PPM. The red LED indicates the PPM and blue/purple indicates S-BUS.



3.4 How to Disarm

(Use T8FB as an example)

Throttle on left stick: move the left stick to the lower right corner, keep about 2 seconds till green LED on.



Throttle on right stick: move the left stick to the lower right corner and the right(throttle) stick to the lower position, keep about 2 seconds till green LED on.



Disarm Gesture



3.5 How to Arm:

Move the throttle stick to the lower position and rudder stick, keep about 2 seconds till green LED off.



Arm Gesture

4. Low Voltage Alarm

The green LED of flight controller CS360 is blinking all the time indicate that the voltage of F110 is lower than 3.8V(we default F110 is ready to alarm if the battery lower than 3.8V), please prepare for charge your battery.

5. Flight Controller CS360 Introduction

Brand new self-developed flight controller system CS360, breaking the defects of Euler angles singular value, using rotation vector algorithms ensure the F110 can fly in angle mode even under high-speed.

CS360 support both coreless and brushless motor, compatible all kinds of quadcopters.

There's six output port, including a battery voltage testing port and a buzzer connect port to indicate disarm or low voltage.

The power supply of CS360 support 1S(4.2V) or 2S(8.4V) or BEC(+5V). Power supply with a 2S battery will make the F110 more powerful, but you have to change the motors that support 2S battery.

When use 1S battery: the camera will powered by the 1S battery directly.

When use 2S battery: the current of camera is 0.5A, the voltage is 5V, camera you bought from Radiolink, come with F110 is not support 2S battery.

BL(bonding pad): short circuit the bonding pad indicates the CS360 is brush mode while without short circuit indicates brushless mode(use brushless BEC). CS360



support almost all kinds of coreless motors including 1020.

Size of PCBA: 21*32* 1.2mm.

Attention: Please make sure the voltage of battery before power on your F110, choose BL 1S or BL 2S if you want to DIY, do not short circuit the three BL at the same time.



6. Read Before Use F110

6.1 Read Before Start to Flight

(1) Since F100 have not Altitude Hold so far, keep the throttle stick smoothly to avoid F110 suddenly drastically up and down.

(2) Put the throttle stick to the lower position immediately to let motor stop work when F110 knock something.

(3) Let the motor be perpendicular to F110 plate.



RadioLink

6.2 Read Before try the Throw and Fly Mode

(1) Make sure you can control F110 skillful and at a pretty wide open space to try the Throw and Fly Mode.

(2) Make sure the head direction and then throw and fly the F110.

(3) Push the throttle stick as soon as throw your F110 and try your best throw it upward.

(4) F110 can correct attitude and direction automatically. If you throw F110 too hard, it may fly to a direction all the time because of the inertia, you can correct the direction by move sticks.

7. Flight Mode

RadioLink racing drone F110 have Stabilize Mode and Low Speed Mode so far.

7.1 Stabilize Mode

AT9S/AT9/AT10/AT10II: Move SwC to the up or center position that keep F110 work in Stabilize Mode.

T8FB: Move SwB to the up or center position that keep F110 work in Stabilize Mode.

7.2 Low Speed Mode

AT9S/AT9/AT10/AT10II: Move SwC to the bottom position that keep F110 work in Low Speed Mode.

T8FB: Move SwB to the bottom position that keep F110 work in Low Speed Mode.

Low Speed Mode will slower than Stabilize Mode and with and less angular variation when flight, suggest that RC beginners control with Stabilize Mode.

8. Calibration

Level calibration have finished when you received the F110, you can re-calibrate if you need.

Level Calibration: Please put the F110 on a level surface, the left stick to the lower left position and the right stick to the lower right position, keep about 3 seconds, the green LED will blinking once, power on again, then calibrate success.



9. Components Without FPV

	F110 Spa	re Parts	
-1 \			Additional and additional and additional and additional and additional and additional and additional addi
	FC CS360*1	1S LiPo Battery*1	RX R6DSM *1
F110 main plate*1			RadioLink
	Propeller*4	1S LiPo battery charger CM120	Packing Box

With FPV





10. Details about FPV



Specs:

AIO FPV camera realize 25mW 40ch 5.8GHz TX, circular polarization clover leaf antenna and great cMos killer 800TVL FPV camera all 3 functions in one limit size and weight unit. Aluminum case and easy mounting design make it great for smaller scale FPV race drones. It's perfect for NTSC and PAL as built-in one button switch!

		Product Specification								
		Model	5.8G	25mW	40Cha	nnels R	F Came	era		
F	1	Video Format						NTSC	C/PAL	
		characteristics		Value				Unit		
			Min	Тур	Max					
		Out Frequency	5645		5945			Mhz		
	2	Out Power	12	13	14			dBm		
	3	Operating Voltage	3	3.7	5.5			V		
	4	Supply Current		0.45				Α		
	5	operating Temperature	-20		85			°C		
	6	Image sensor						1/3 C	MOS	
	7	Resolution Lines						800T	VL	
	8	Weight		8			g			
Γ	9	Antenna	5.8G	Hz Ban	d Circu	lar Pola	arizatio	n Clov	er Lea	f
Γ	9	FOV	150° Horizontal							
	9	Dimensions(LxWxH)	26x20x18mm							
	10		Frequency channel list(MHZ)							
	11	Band CH	CH1	CH2	СНЗ	CH4	CHS	CH6	CH7	СН8
	12	Band	CIT	CITZ	CIIJ	CITH	CIIJ	CHO	CI1/	CHO
	13	A	5865	5845	5825	5805	5785	5765	5745	5725
\vdash	14	B	5733	5752	5771	5790	5809	5828	5847	5866
\vdash	15	E	5705	5685	5665	5645	5885	5905	5925	5945
\vdash	16	F	5740	5760	5780	5800	5820	5840	5860	5880
L	17	R	5658	5695	5732	5769	5806	5843	5880	5917

