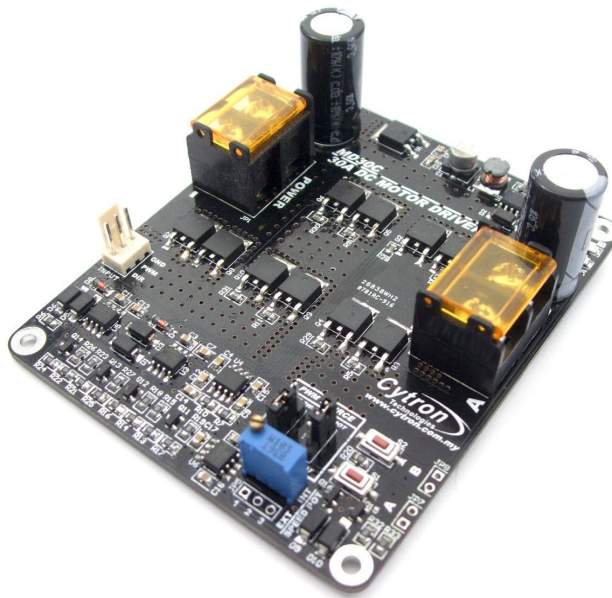




MD30C 30A DC Motor Driver



User's Manual

V1.2

June 2014

Index

1.	Introduction	3
2.	Packing List	4
3.	Product Specification and Limitations	5
4.	Board Layout	6
5.	Dimension	8
6.	Hardware Installation	9
7.	Warranty	16

1.0 INTRODUCTION

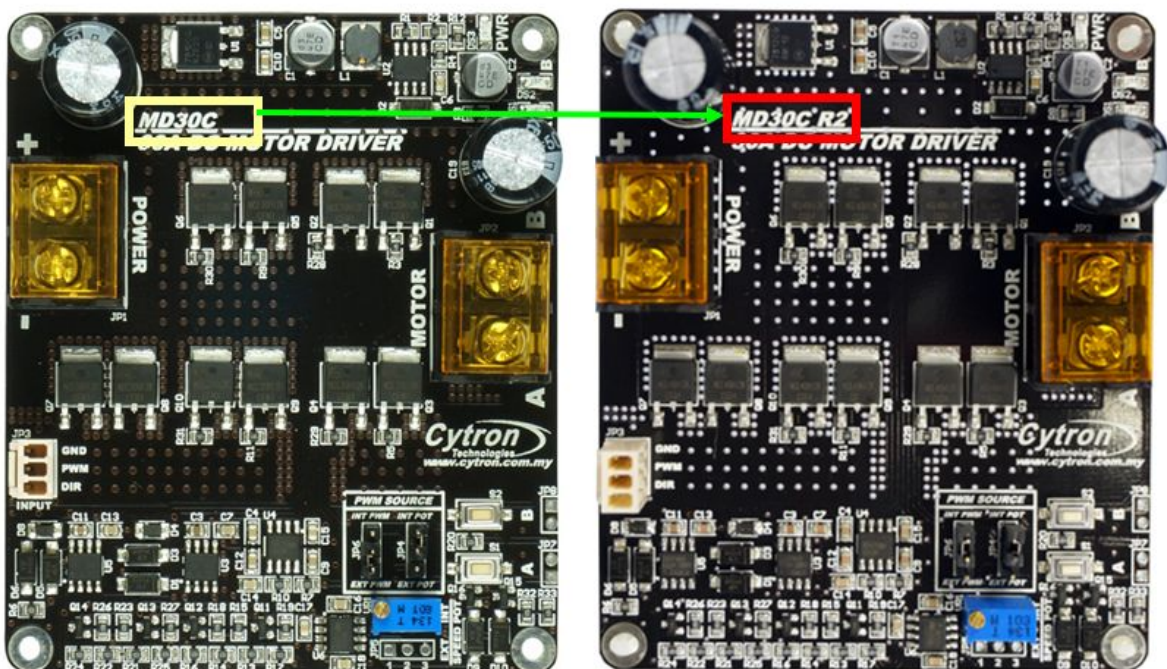
[MD30C](#) is the successor of MD30B which is designed to drive medium to high power brushed DC motor with current capacity up to 80A peak and 30A continuously. Fully NMOS design not only provides faster switching time, it is also more efficient and no heatsink or fan is required.

Besides that, MD30C also incorporates some user friendly features such as reverse polarity protection and onboard PWM generator which allows it to operate without a host controller. The motor can simply be controlled with the onboard switches and speed potentiometer. External switches and potentiometer can also be used.

Features:

- Bi-directional control for 1 brushed DC motor.
- Motor Voltage: 5V - ~~25V~~ 30V.
- Maximum Current: 80A peak (1 second), 30A continuously.
- Reverse polarity protection.
- 3.3V and 5V logic level input.
- Fully NMOS H-Bridge for better efficiency and no heat sink is required.
- Speed control PWM frequency up to 20KHz (Actual output frequency is same as input frequency when external PWM is selected).
- Onboard PWM generator with switches and potentiometer for standalone operation.
- Support both locked-antiphase and sign-magnitude for external PWM operation.

MD30C is now Revision 2.0.

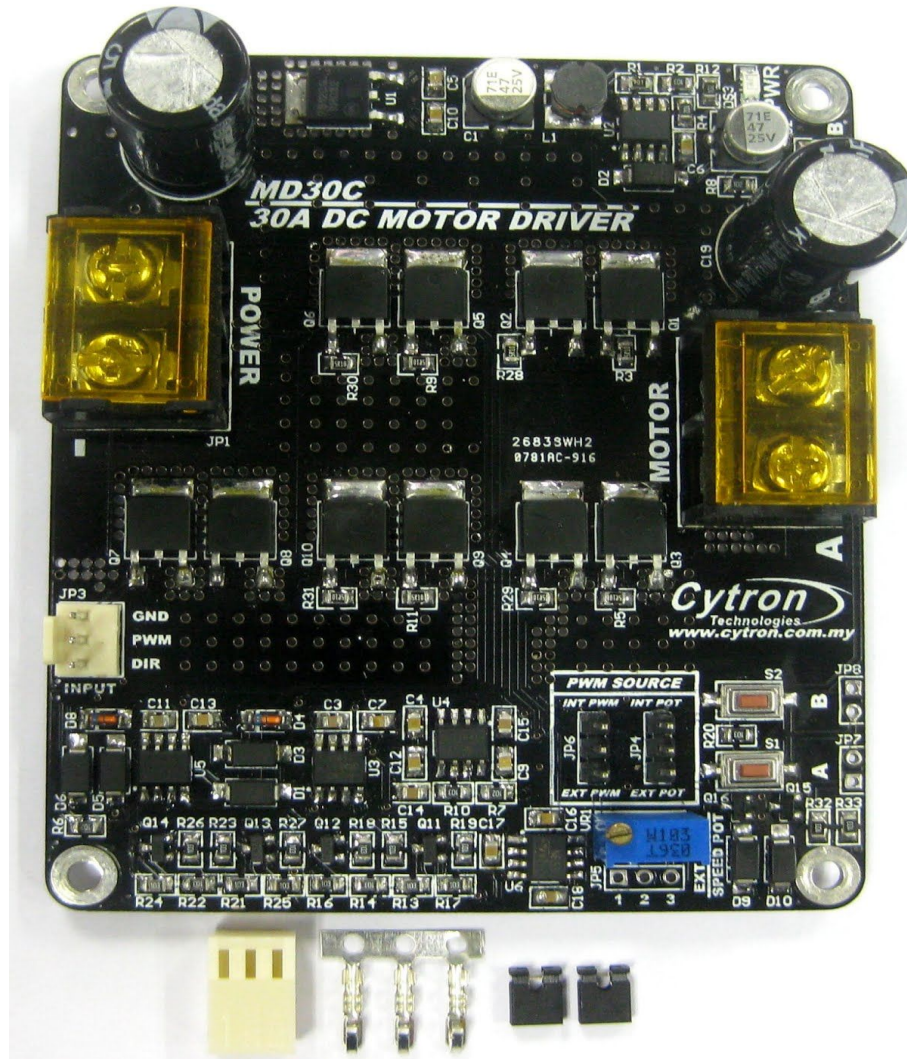


REV 1.0

REV 2.0

2.0 PACKING LIST

Please check the parts and components according to the packing lists. If there are any parts missing, please contact us at sales@cytron.com.my immediately.



1. 1 x [MD30C](#) 30A DC Motor Driver
2. 2 x [Mini Jumper](#)
3. 1 x [2510 PCB Connector](#) - 3 Ways (Female)
4. 3 x [2510 Terminal Pin](#)

3.0 PRODUCT SPECIFICATION AND LIMITATIONS

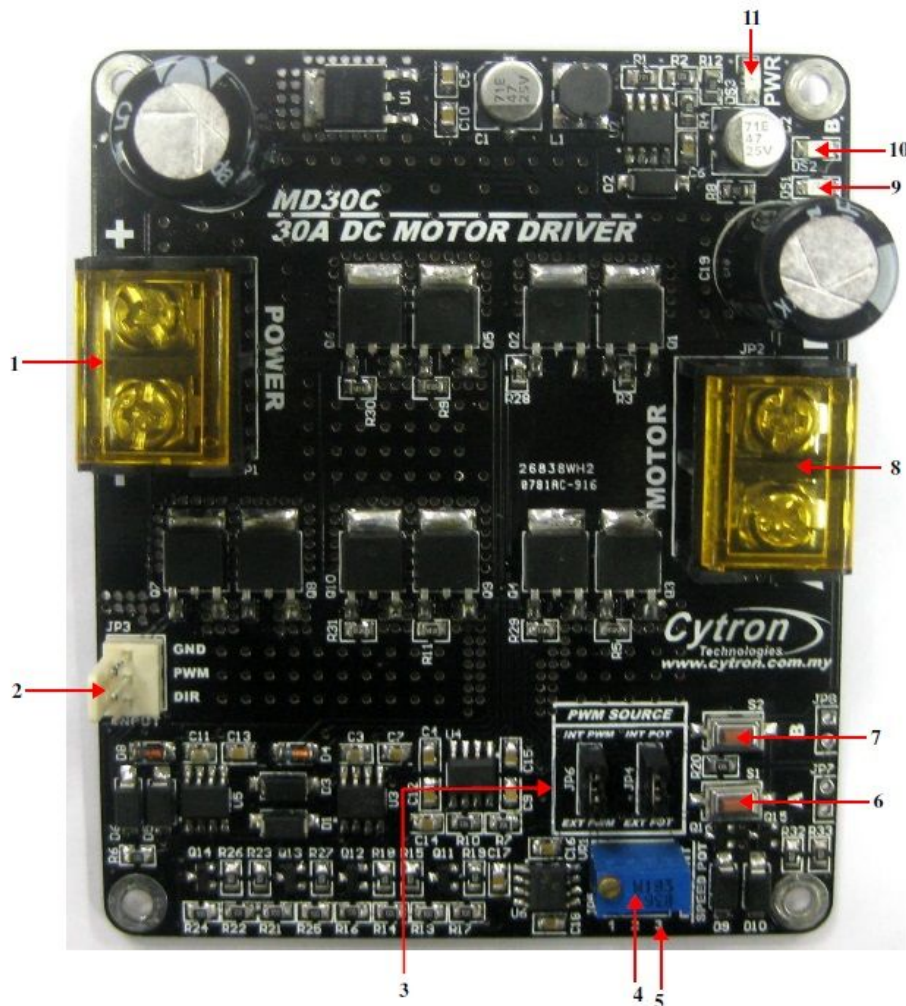
Absolute Maximum Rating

Parameter	Min	Typical	Max	Unit
Power Input Voltage (Motor supply voltage)	5	-	25	V
I _{MAX} (Maximum Continuous Motor Current)	-	-	30	A
I _{PEAK} (Peak Motor Current)*	-	-	80	A
I _{IDLE} (Idle Current)	-	-	100	mA
V _{IOH} (Logic Input-High Level)	3	-	5.5	V
V _{IOL} (Logic Input - Low Level)	0	-	0.5	V
Maximum PWM Frequency**	-	-	20	KHz

****Must not exceed 1 second.***

*****Actual output frequency is same as input frequency when external PWM is selected.***

4.0 BOARD LAYOUT



1. Power Terminal Block

Connect to power source. For high current application, please solder the wire directly to the pad at bottom layer.

2. Input

Pin No.	Pin Name	Description
1	GND	Ground
2	PWM	*PWM input for speed control.
3	DIR	Direction Input.

*Note that it is not for RC PWM

3. PWM Source Selector

Select the source of the speed control PWM.

PWM Source	JP4	JP6
Internal Potentiometer	INT POT	INT PWM
External Potentiometer	EXT POT	INT PWM
External PWM Signal	X (Don't Care)	EXT PWM

4. Internal PWM Potentiometer

Used to control the motor speed when PWM source is internal potentiometer.

5. External PWM Potentiometer Port

Connect to the external potentiometer (5K - 10K Ohm). Used to control the motor speed when PWM source is external potentiometer.

6. Test Button A

When this button is pressed, current flows from output A to B and motor will turn CW (or CCW depending on the connection). External switch can also be connected for the ease of access.

7. Test Button B

When this button is pressed, current flows from output B to A and motor will turn CCW (or CW depending on the connection). External switch can also be connected for the ease of access.

8. Motor Terminal Block

Connect to motor. For high current application, please solder the wire directly to the pad at bottom layer.

9. Red LED A.

Turns ON when the output B is low and output A is high. Indicates the current flows from output A to B.

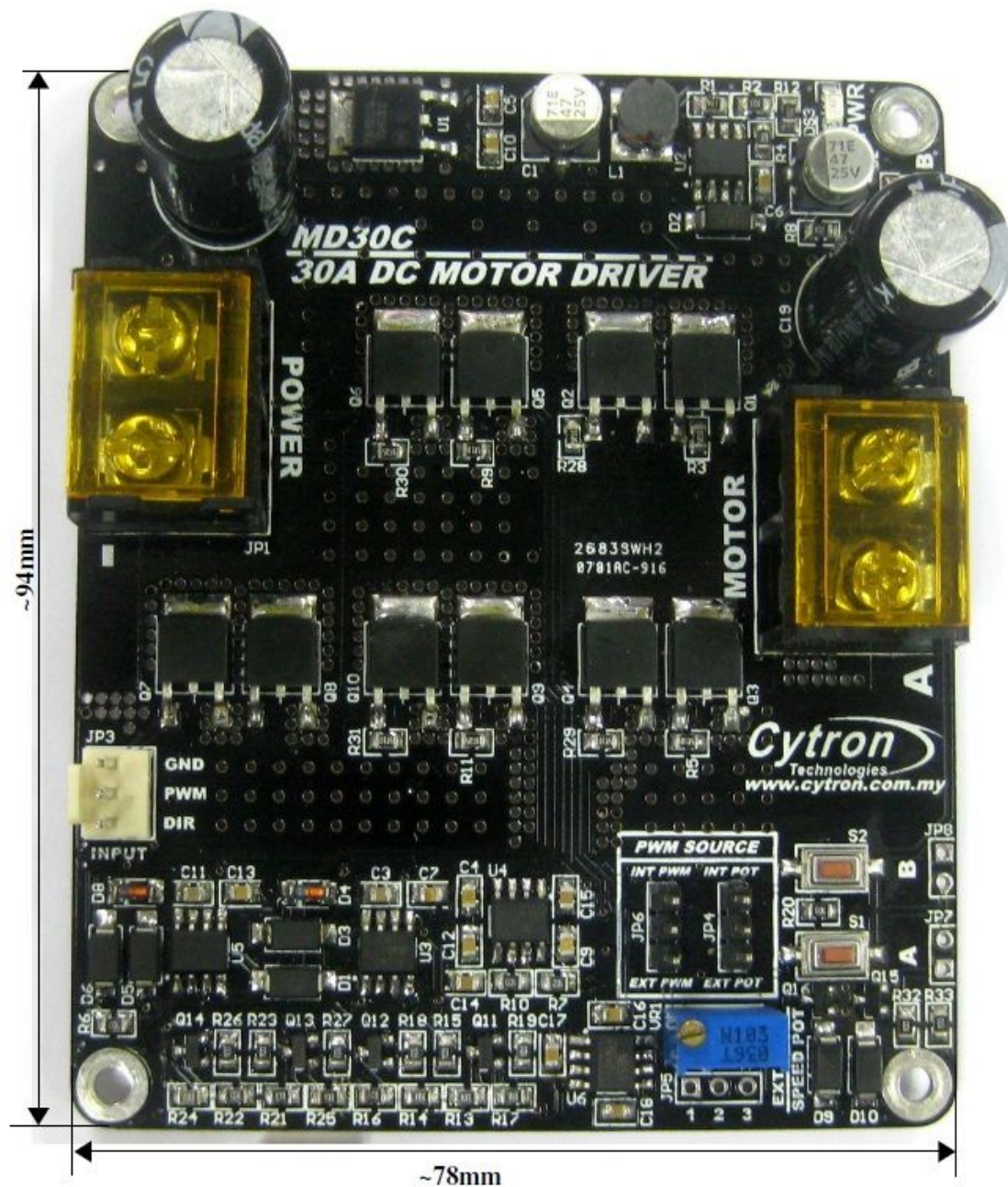
10. Red LED B

Turns ON when the output A is low and output B is high. Indicates the current flows from output B to A.

11. Green Power LED

Turn on when the MD30C is powered up.

5.0 DIMENSION



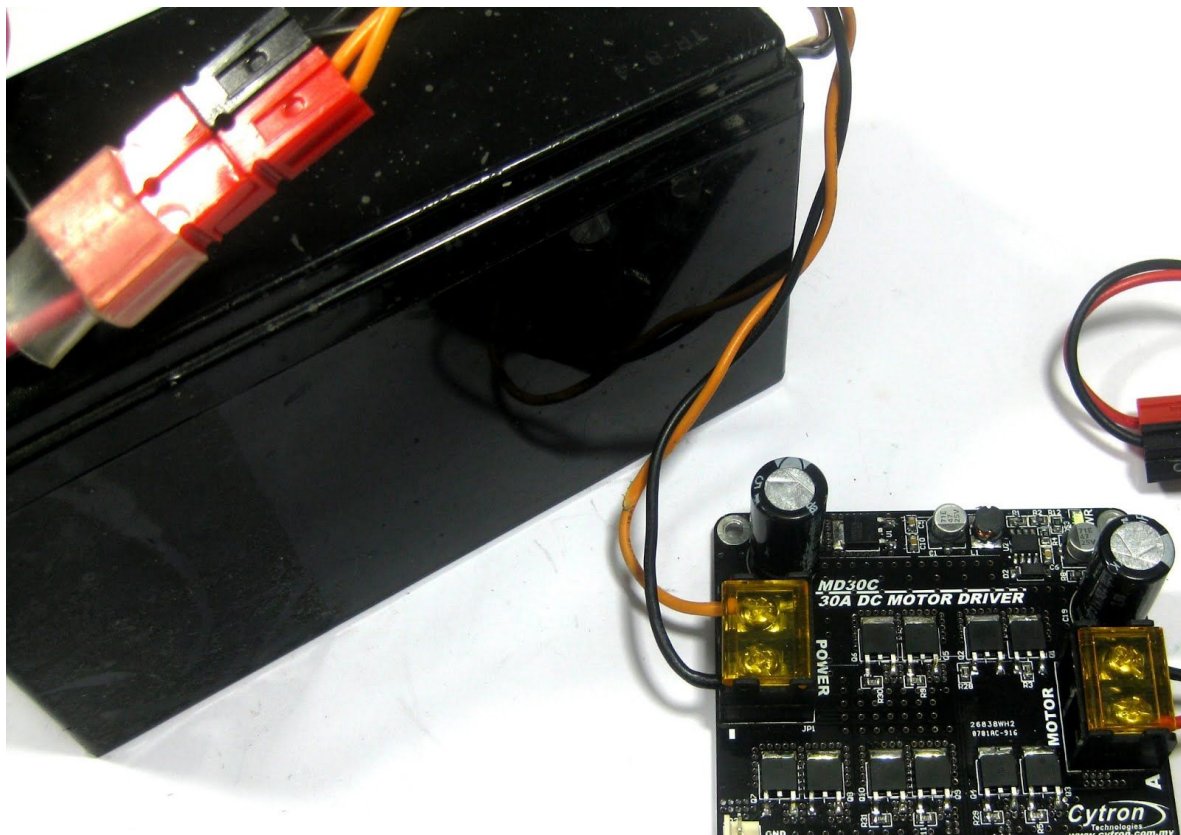
6.0 HARDWARE INSTALLATION AND GETTING STARTED

6.1 Battery and Motor Connection

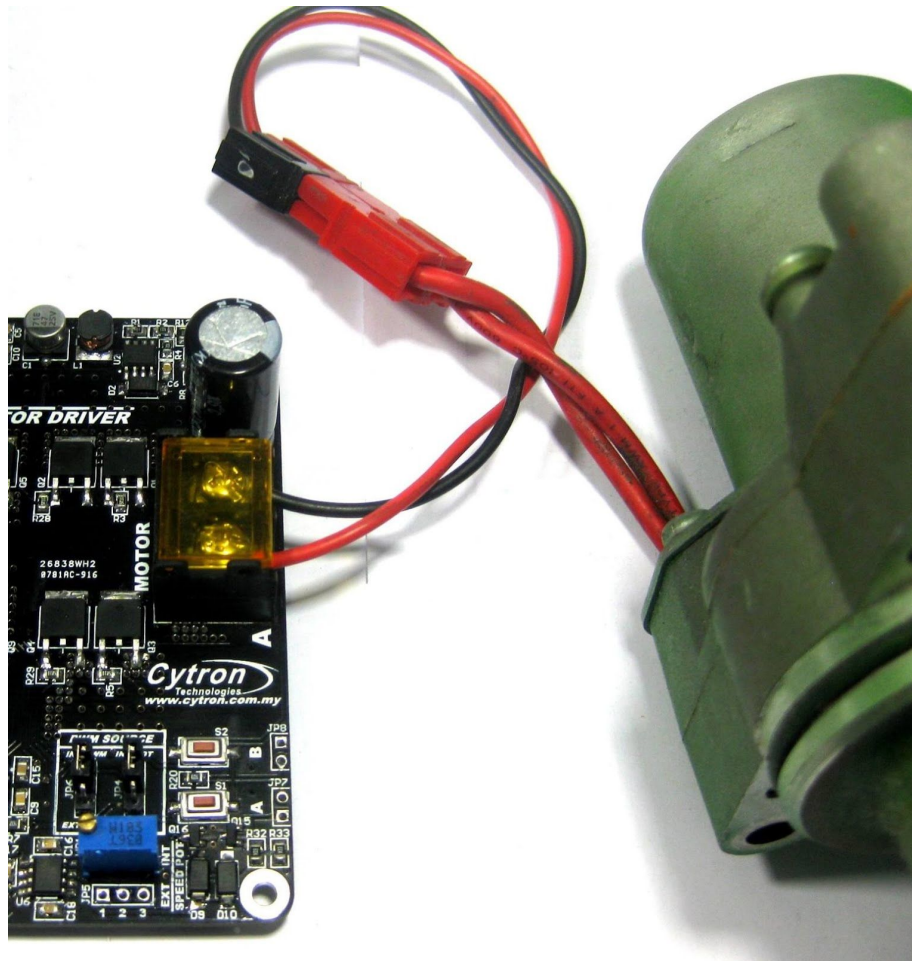
Battery and motor can be connected to the [MD30C](#) either via the screw terminal block, or it can be soldered directly to the pad at the bottom layer of the PCB. Make sure the battery and motor are connected to the correct port. Connecting battery to the motor port will burn the MOSFET.

NOTE:

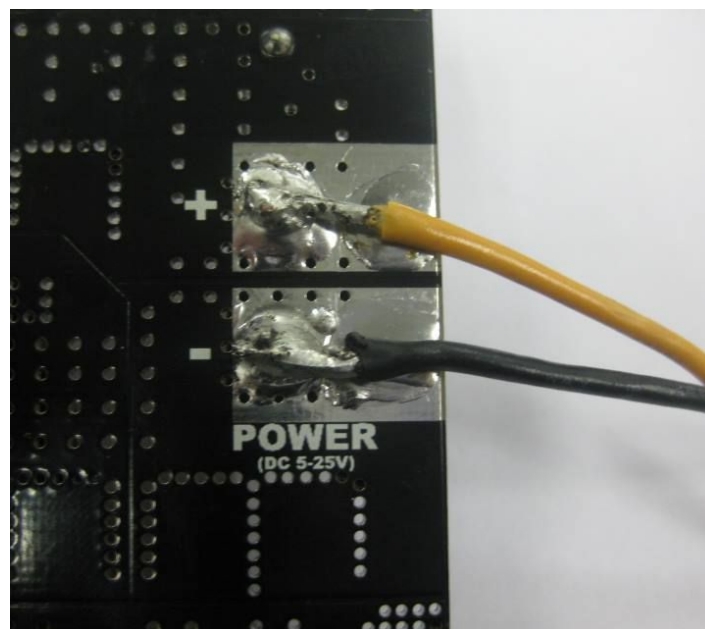
For application where the current is $> 20A$, it's recommended to solder the wire directly to the pad at bottom layer.



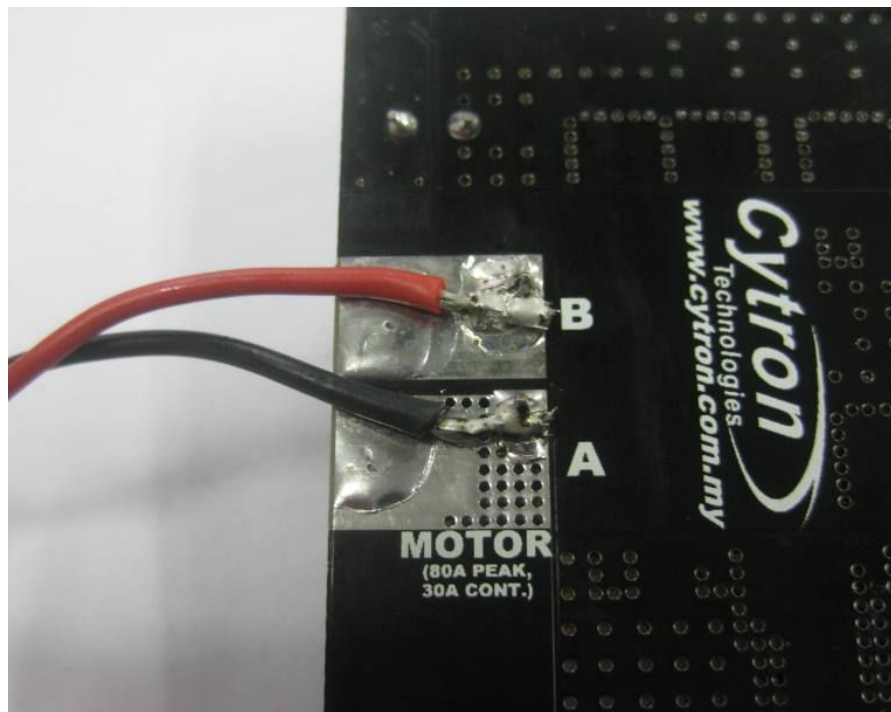
Battery is connected to MD30C via terminal block



Motor is connected to MD30C via terminal block



Battery is soldered directly to MD30C



Motor is soldered directly to MD30C

6.2 Standalone Operation

The [MD30C](#) can operate in standalone mode. In this mode, the motor is controlled by the onboard switches and speed potentiometer. Alternatively, external switches and potentiometer can be used to control the motor. This allow the switches and potentiometer to be mounted at easy to reach place.

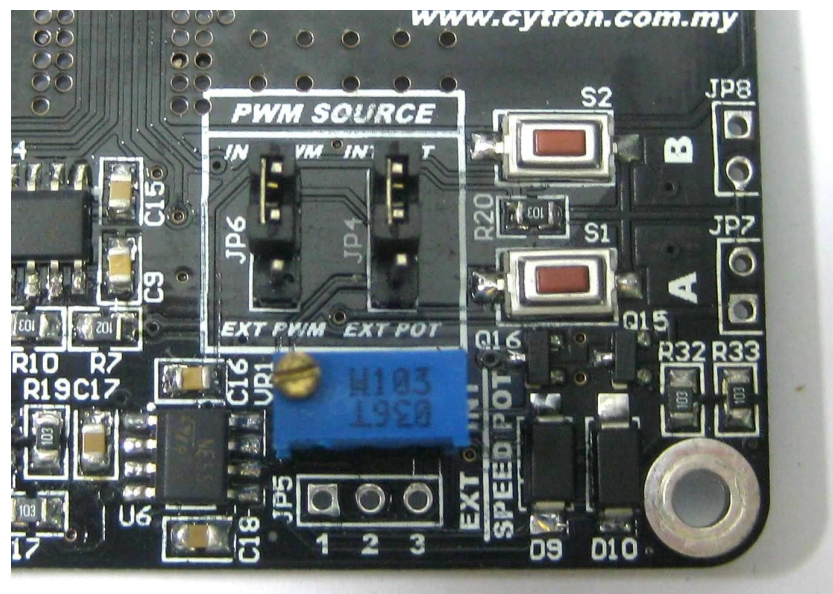
Onboard Switches and Potentiometer

Set the jumpers as below:

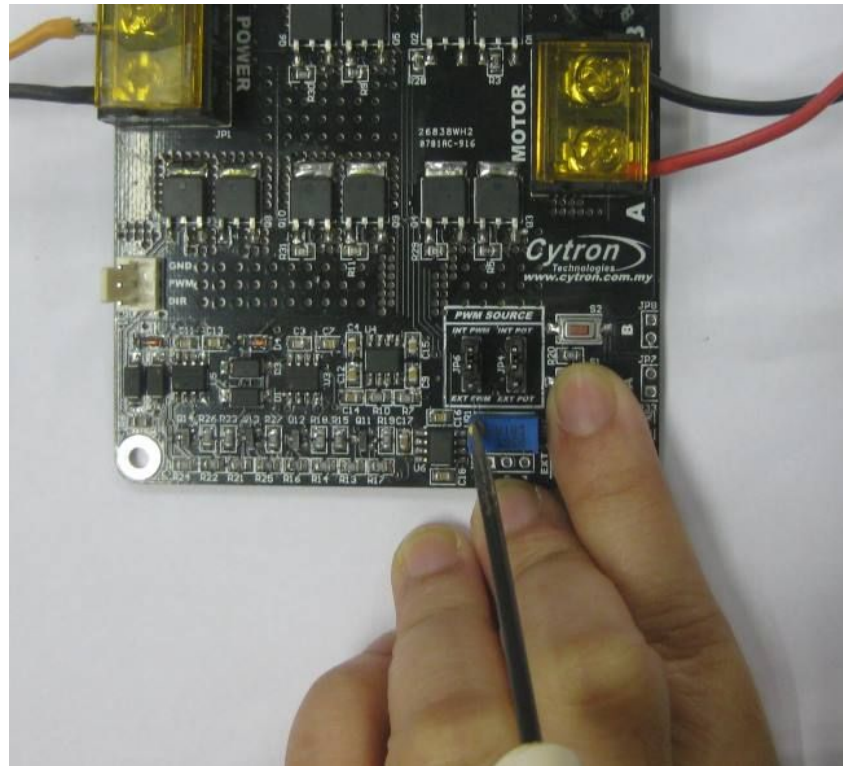
JP4 : INT POT

JP6 : INT PWM

After that, connect the battery and motor to the MD30C. Pressing switch A will run the motor in CW direction and pressing switch B will run the motor in CCW direction (The actual direction is depending on the motor polarity). The speed of the motor can be controlled by the onboard speed potentiometer.



Don't worry if the motor does not run when the switch is pressed. This might be due to the set speed is too low for the motor to run. Try turning the speed potentiometer CW for a few round while pressing down one of the switch to increase the motor speed.



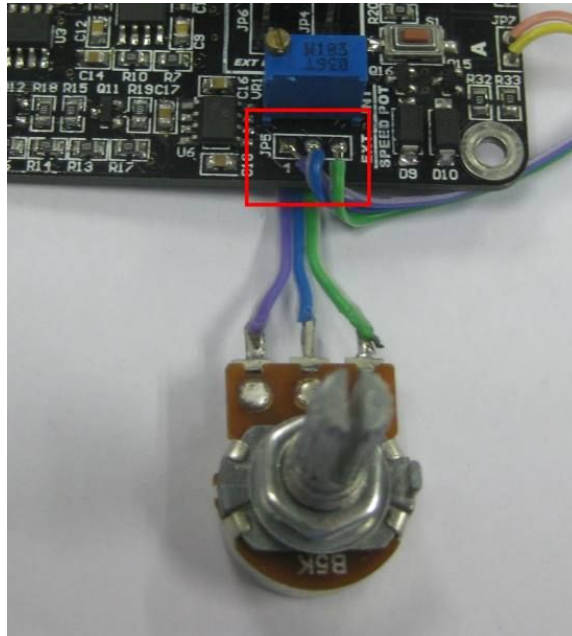
External Switches and Potentiometer

Set the jumpers as below:

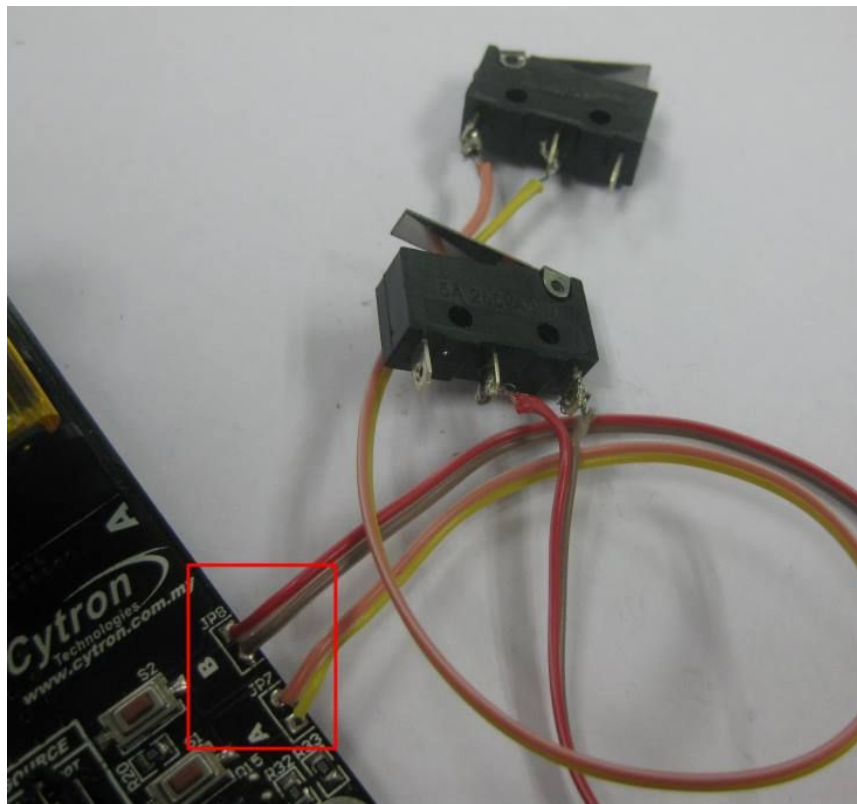
JP4 : EXT POT

JP6 : INT PWM

Connect the external switches and potentiometer as below. Please note that the onboard potentiometer will have no effect when JP4 is changed to EXT POT.



External potentiometer is connected on JP5



External switch is connected to JP7 and JP8

6.3 Interface with Microcontroller

To control the motor with a microcontroller, set the jumpers as below:

JP4 : Don't Care

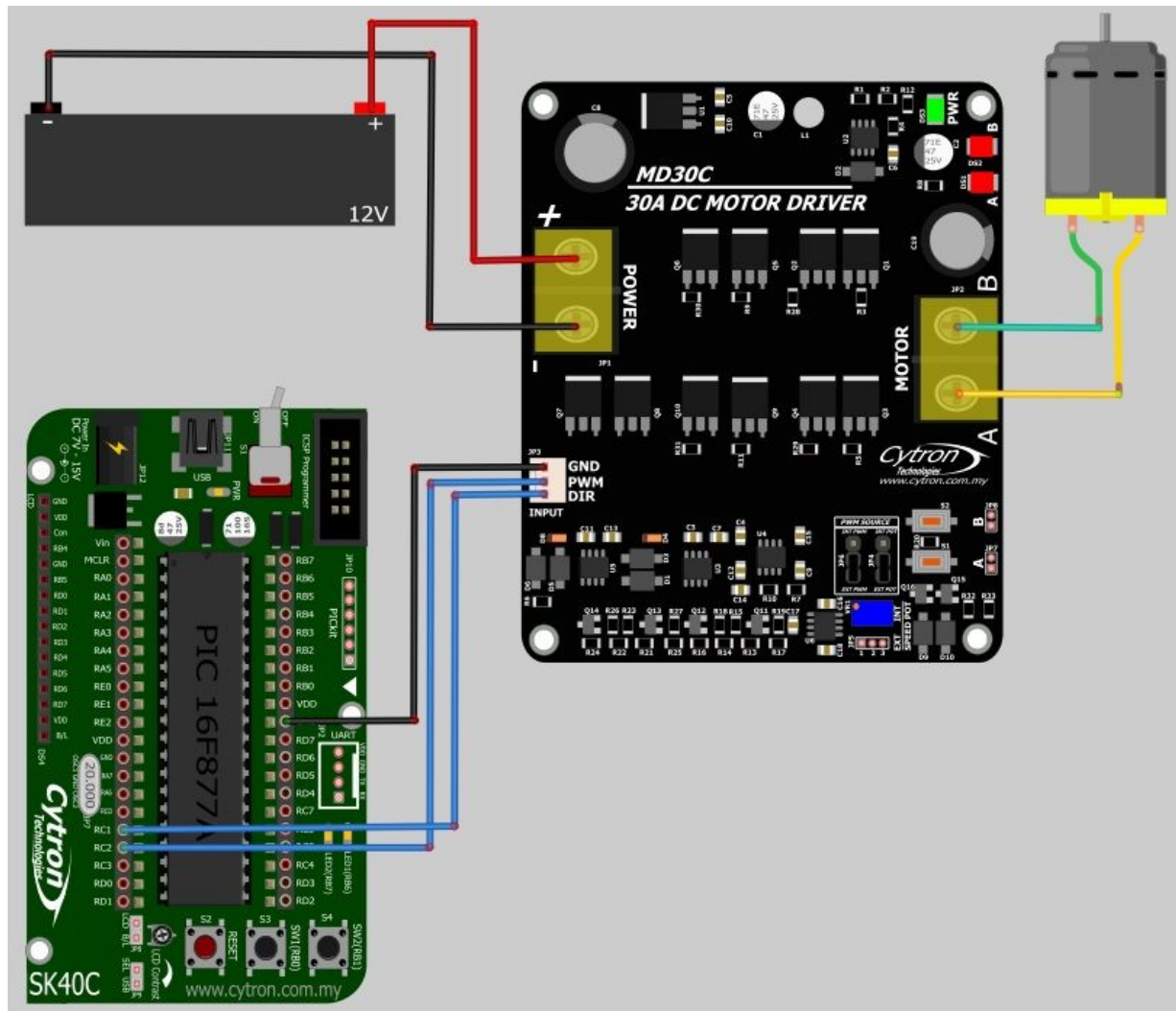
JP6 : EXT PWM

Truth table for the control logic:

PWM	DIR	Output A	Output B
Low	X (Don't Care)	Low	Low
High	Low	High	Low
High	High	Low	High

****** Please do note that to set either DIR or PWM pin at LOW condition first when power is on.

Picture below shows an example of connecting the [MD30C](#) to the [SK40C](#).



7.0 WARRANTY

- Product warranty is valid for 6 months.
- Warranty only applies to manufacturing defect.
- Damaged caused by misuse is not covered under warranty
- Warranty does not cover freight cost for both ways.

Prepared by
Cytron Technologies Sdn. Bhd.
No. 16, Jalan Industri Ringan Permatang Tinggi 2,
Kawasan Industri Ringan Permatang Tinggi,
14100 Simpang Ampat,
Penang, Malaysia.

Tel: +604 - 504 1878

Fax: +604 - 504 0138

URL: www.cytron.com.my

Email: support@cytron.com.my

sales@cytron.com.my